

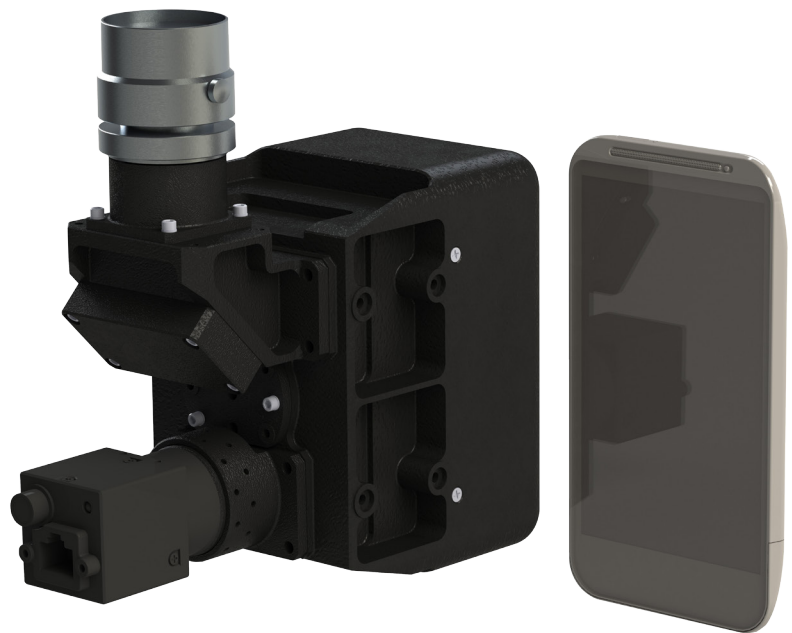


# MICRO CASI 1920

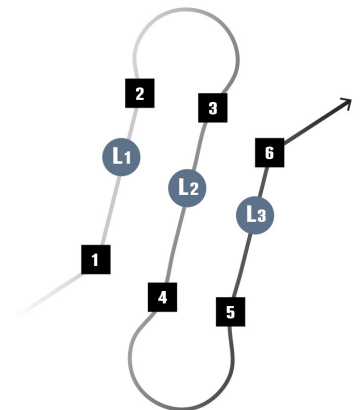
SMALL FORM FACTOR, 288 CHANNEL,  
PROGRAMMABLE, WIDE ARRAY  
HYPER SPECTRAL PUSHBROOM VNIR IMAGER

PORTABLE HYPER SPECTRAL MICRO-VNIR IMAGER FOR AIR & GROUND USE

- Portable Air/Ground Hyperspectral VNIR Imager
- 0.4–1.0µm Spectral Coverage
- Self-Contained Camera & Data Recording
- 288 Spectral Channels
- 36.6° FOV
- 1920 Spatial Imaging Pixels
- Custom Fore-Optics Available
- Optional GPS/IMU
- Internal Calibration System
- Easy Lidar Integration
- Remote Operation via R/F Link or  
Autonomous via Waypoints
- Precision Data Time Stamping to External Devices
- API Available



Control via R/F Link



or Waypoints



HYPER SPECTRAL & THERMAL REMOTE SENSING

# microCASI1920

SMALL FORM FACTOR, 288 CHANNEL, WIDE ARRAY, HYPERSPECTRAL PUSHBROOM VNIR IMAGER, CONTINUOUS VNIR-SWIR COVERAGE WHEN USED WITH ITRES  $\mu$ SASI-384

Vegetation Classifications / Invasive Species / Optical Water Quality / Coral Reefs / Wetlands / Forestry / Agriculture / Change Detection / Environmental Impact Assessments / Utility Corridors

## PERFORMANCE

<b>Spectral Range (Continuous Coverage)</b>	400-1000nm
<b># Spectral Channels</b>	288
<b># Across-Track Pixels</b>	1920
<b>Total Field of View</b>	36.6 degrees
<b>IFOV</b>	0.36 mRad (0.021°)
<b>f/#</b>	f/2.0
<b>Spectral Width Sampling/Row</b>	2.1nm (average)
<b>Spectral Resolution (FWHM)</b>	<5nm
<b>Pixel Size</b>	5.86 x 5.86 microns
<b>Dynamic Range</b>	12-bits
<b>Detector Full Well</b>	32,500 electrons
<b>Maximum FPS:</b>	280 fps (full frame)
<b>Spectral Smile/</b>	≤0.5 pixels
<b>Keystone Distortion</b>	≤0.5 pixels
<b>Data Recording Capacity</b>	480GB (SSD, SATA III)
<b>Data Recording Capacity (hr)</b>	3 hours (@ 40fps)

## DIMENSIONS, WEIGHTS, AND POWER

ITEM	W / H / D (CM) / WT. (KG)
<b>SHU, Control, Recording</b>	10.2 / 19 / 17.8 / <1.5kg <sup>1</sup>
<b>Power Draw</b>	Sensor Head 45W <sup>1</sup> <sup>1</sup> Subject to change

## OPERATION

<b>Operator</b>	Control remotely via laptop & existing R/F downlink, or pre-programmed track and waypoints.
<b>Multiple Sensor Operation</b>	Up to 5 ITRES imagers may be simultaneously operated via MuSIC system

## INTERFACE, TIME-STAMPING, REMOTE OPERATION & CONTROL

- GigE or USB-3
- TTL input for waypoint trigger
- Precision data time-stamping to external devices
- API available

## DATA PROCESSING SYSTEM

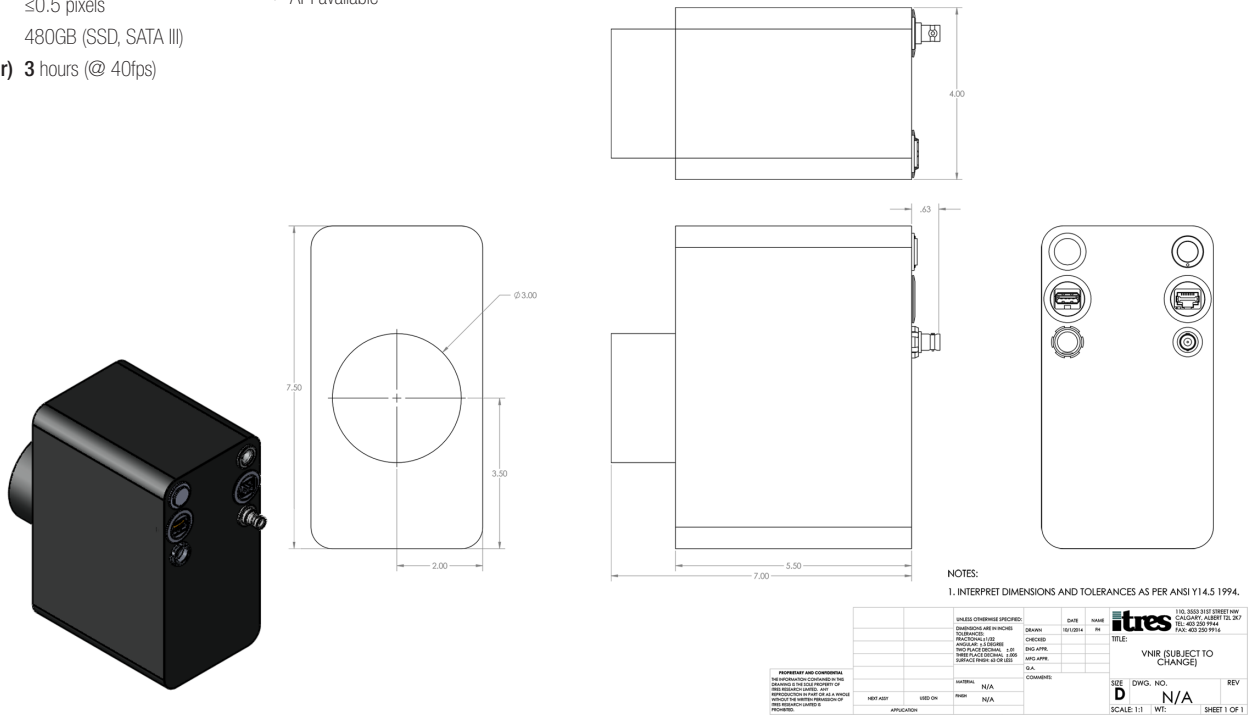
- Processing software Linux or Windows-based
- Playback software (Quicklook)
- Generates 16-32 bit BIP format data compatible with ENVI (BIL, BSQ formats possible)

## GEOCORRECTION SYSTEM

- GPS/IMU integration (optional)
- Data synchronization (GPS, attitude, & image streams, if INS used)

## GEOCORRECTION/ORTHO CORRECTION/MOSAICKING SOFTWARE

- Accepts Lidar, Ifsar, and USGS DEM inputs
- Nearest neighbor algorithm used – maintains radiometric fidelity



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All ITRES sensors are calibrated to traceable standards.  
Specifications subject to change without notice.